

# On the asymptotic geometry of finite-type $k$ -surfaces in 3-dimensional hyperbolic space



Graham Andrew Smith

Universidade Federal do Rio de Janeiro

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# Definitions

$\mathbb{H}^3$  is 3-dimensional hyperbolic space.

A  **$k$ -surface** in a pair  $(S, e)$ , where  $S$  is a smooth surface and  $e : S \rightarrow \mathbb{H}^3$  is an immersion of constant extrinsic curvature equal to  $k$ .

A  $k$ -surface has **finite type** whenever the induced metric is complete and has finite area.

## Examples - Fermi coordinates

The Fermi metric of  $\mathbb{H}^2$  about a complete geodesic is

$$g = dr^2 + \cosh(r)^2 dt^2.$$

If  $\gamma := (r, t) : \mathbb{R} \rightarrow \mathbb{R}^2$  satisfies

$$r(s) = \operatorname{arcsinh}(A \cosh(\sqrt{1-k}s) + B \sinh(\sqrt{1-k}s)) \text{ and}$$
$$\dot{h}(s)^2 = \frac{1}{\cosh(r(s))^2} (1 - \dot{r}(s)^2),$$

then the surface of revolution  $\Sigma_k(A, B)$  generated by rotating  $\gamma$  about the  $t$ -axis is a  $k$ -surface.

## Examples - Types of surfaces of revolution

$\lim_{B \rightarrow 0} \Sigma_k(0, B)$  is the unit normal circle bundle over a complete geodesic.

This models degenerate limits of sequences of  $k$ -surfaces.

When  $A > 0$ ,  $\Sigma_k(-A, -A)$  has a finite area cusp at  $+\infty$ .

This models the geometry at infinity of finite-type  $k$ -surfaces.

## $k$ -ends and abstract $k$ -ends

The Fermi metric of  $\mathbb{H}^3$  about a complete geodesic is

$$g = dr^2 + \sinh(r)^2 d\theta^2 + \cosh(r)^2 dt^2.$$

Given  $f : mS^1 \times [0, \infty[ \rightarrow \mathbb{R}$ , define  $e_f : mS^1 \times [0, \infty[ \rightarrow \mathbb{H}^3$  by

$$e_f(\theta, t) := (f(\theta, t), \theta, t).$$

We call  $e_f$  a  $k$ -**end** of **order**  $m$  whenever it has constant extrinsic curvature equal to  $k$  and

$$\lim_{t \rightarrow +\infty} f(\theta, t) = 0.$$

We call  $f$  and **abstract  $k$ -end** of **order**  $m$  whenever this holds.

Every abstract  $k$ -end satisfies

$$f(\theta, t) = Ae^{-\sqrt{1-k}t} + o(e^{-\sqrt{1-k}t}).$$

## The first structure theorem

**Theorem A** - Let  $(S, e)$  be a finite-type  $k$ -surface. There exists a compact subset  $K \subseteq S$  such that  $(S \setminus K, e)$  is a disjoint union of finitely many finite-order  $k$ -ends.

## The horizon map

The **horizon map**  $h : \mathbb{U}\mathbb{H}^3 \rightarrow \partial_\infty \mathbb{H}^3 = \hat{\mathbb{C}}$  is defined by

$$h(u) := \lim_{t \rightarrow +\infty} \gamma_u(t),$$

where  $\gamma_u : \mathbb{R} \rightarrow \mathbb{H}^3$  is the unique unit speed geodesic such that  $\dot{\gamma}_u(0) = u$ .

Let  $(S, e)$  be a  $k$ -surface. Let  $N_e : S \rightarrow \mathbb{U}\mathbb{H}^3$  be its unit normal vector field. Define

$$\phi_e(x) := h \circ N_e.$$

This is a local homeomorphism and  $S$  carries a unique holomorphic structure  $\phi^* \hat{\mathbb{C}}$  that makes  $\phi_e$  holomorphic.

## The second structure theorem

**Theorem B** - Let  $(S, e)$  be a finite-type  $k$ -surface.  $S = \bar{S} \setminus P$ , where  $\bar{S}$  is a closed Riemann surface and  $P \subseteq \bar{S}$  is finite. Moreover

(1)  $\phi_e$  extends to a holomorphic function  $\bar{\phi}_e : \bar{S} \rightarrow \hat{\mathbb{C}}$ , the ramification points of  $\bar{\phi}_e$  are elements of  $P$  and, for all  $p \in P$ , its ramification order at  $p$  is equal to  $(m_p - 1)$ , where  $m_p$  is the winding order of the end at  $p$ ; and

(2)  $e$  extends to a continuous function  $\bar{e} : \bar{S} \rightarrow \mathbb{H}^3 \cup \hat{\mathbb{C}}$  such that, for all  $p \in P$ ,  $\hat{e}(p) = \hat{\phi}_e(p)$ .



## A parametrization theorem

A **pointed ramified covering** of  $\hat{\mathbb{C}}$  is a triple  $(\bar{S}, P, \phi)$  where  $\bar{S}$  is a closed Riemann surface,  $P \subseteq \bar{S}$  is a finite subset, and  $\phi : \bar{S} \rightarrow \hat{\mathbb{C}}$  is a holomorphic function with ramification points in  $P$ .

$\mathcal{R}$  is the space of pointed ramified coverings of  $\hat{\mathbb{C}}$ .

**Theorem C** - For all  $k \in ]0, 1[$  and for all  $(\bar{S}, P, \phi) \in \mathcal{R}$ , there exists a unique finite-type  $k$ -surface  $e := e_\phi : \bar{S} \setminus P \rightarrow \mathbb{H}^3$  such that  $\phi_e = \phi$ .

# The space of $k$ -surfaces

The space of finite-type  $k$ -surfaces identifies with  $\mathcal{R}$ .

$\mathcal{R}$  is stratified by smooth complex manifolds locally parametrized by the images  $(\phi(p_1), \dots, \phi(p_m))$  of the generalized ramification points  $P := (p_1, \dots, p_m)$ .

For each  $i$ , we call  $z_i := \phi(p_i)$  the  $i$ 'th **extremity** of  $e_\phi$ .

## Preferred geodesics

Every  $k$ -end is asymptotic to a unit-speed geodesic.

All unit-speed geodesics with the same end-point are asymptotic to one-another (up to translation).

However,  $k$ -ends have preferred geodesics.

## Steiner curvature centroids

Consider first a convex subset  $K \subseteq \mathbb{R}^2$  with support function  $f : S^1 \rightarrow \mathbb{R}$ .

Its **Steiner curvature centroid** is the first Fourier mode of  $f$ .

For triangles, it is the centre of mass obtained by placing weights at each vertex equal to the angle at that vertex.

This provides a concept of centre which is equivariant with respect to Minkowski addition.

This concept extends to locally strictly convex curves.

## Steiner curvature centroids and $k$ -ends

$\gamma : \mathbb{R} \rightarrow \mathbb{H}^3$  is a unit-speed geodesic.

$e : mS^1 \times [0, \infty[ \rightarrow \mathbb{H}^3$  is a  $k$ -end about  $\gamma$ .

For all  $t$ ,  $H_t$  is the unique horosphere centred on  $\gamma(+\infty)$  passing through  $\gamma(t)$ .

For sufficiently large  $t$ ,  $e \pitchfork H_t$ .

Let  $c_{e,\gamma}(t)$  be the Steiner curvature centroid of this curve.

## The third structure theorem

**Theorem D** - Let  $e : mS^1 \times [0, \infty[ \rightarrow \mathbb{H}^3$  be a  $k$ -end. There exists a unique unit-speed geodesic  $\gamma : \mathbb{R} \rightarrow \mathbb{H}^3$  such that

$$d(\gamma(t), c_{e,\gamma}(t)) = O(e^{-\sqrt{4-3k}t}).$$

We call this geodesic the **Steiner geodesic** of the  $k$ -end.

The extremity  $z$  of this end is an end-point of the Steiner geodesic.

We call the other end-point  $w$  of the Steiner geodesic the **Steiner point** of end.

## A balancing formula

$(S, e)$  is a finite-type  $k$ -surface.  $P$  is its set of ends.

For each  $p \in P$ ,  $m_p$  is the winding order,  $z_p$  the extremity and  $w_p$  the Steiner point of the end at  $p$ .

For each  $p \in P$ , the **Steiner vector** of the  $p$ 'th end is defined by

$$\zeta_p := \frac{1}{w_p - z_p}.$$

**Theorem D** - The Steiner vectors satisfy

$$\sum_{p \in P} m_p \zeta_p = 0.$$

Möbius invariance yields two other relations.

## Lagrangian immersions

$(\bar{S}, P, \phi)$  is a ramified cover of  $\hat{\mathbb{C}}$ .

$\mathcal{R}_0$  is the stratum of  $\mathcal{R}$  containing  $(\bar{S}, P, \phi)$ .

$\omega_0$  is the symplectic form defined over  $\hat{\mathbb{C}} \times \hat{\mathbb{C}} \setminus \Delta$  by

$$\omega_0 := \operatorname{Re} \left( \frac{1}{(z-w)^2} dz \wedge dw \right)$$

**Theorem E** - The function  $F := (z_1, w_1, \dots, z_N, w_N)$  is a lagrangian immersion from  $\mathcal{R}_0$  into  $(\hat{\mathbb{C}} \times \hat{\mathbb{C}} \setminus \Delta)^N$  furnished with the symplectic form

$$\omega := (m_1 \omega_0) \oplus \dots \oplus (m_N \omega_N).$$



## Darboux coordinates

In the upper half-space model,

$$\text{U}\mathbb{H}^3 = \{(x, y, z, u, v, w) \mid z > 0, u^2 + v^2 + w^2 = z^2\},$$

with contact form

$$\alpha := \frac{1}{z^2}(udx + vdy + wdz).$$

**Darboux coordinates** about a complete geodesic are

$$\Phi(x, y, u, v, t) := e^y \left( t \cos(x) - u \sin(x), t \sin(x) + u \cos(x), 1, \frac{-\cos(x)}{\sqrt{1 + (t + v)^2}}, \frac{-\sin(x)}{\sqrt{1 + (t + v)^2}}, \frac{(t + v)}{\sqrt{1 + (t + v)^2}} \right).$$

## Abstract $k$ -ends and Darboux coordinates

For  $f : mS^1 \times [0, \infty[ \rightarrow \mathbb{R}$ ,  $\hat{f} : mS^1 \times [0, \infty[ \rightarrow \mathbb{R}$  is

$$\hat{f}(\theta, t) := \Phi(\theta, t, f_\theta(\theta, t), f_t(\theta, t), t).$$

$f$  is an abstract  $k$ -end whenever

$$kf_{\theta\theta} + f_{tt} - (1 - k)f = F(f, Df, D^2f),$$

where  $F$  is analytic, vanishing up to order 2 at  $(0, 0, 0)$ .

## Separation of variables

If  $f : S^1 \times [0, \infty[ \rightarrow \mathbb{R}$  is bounded and solves

$$f_{\theta\theta} + f_{tt} - c^2 f = 0,$$

then

$$f = \sum_{m \in \mathbb{Z}} a_m e^{im\theta} e^{-\sqrt{c^2 + m^2} t}$$

## Nonlinear separation of variables

If  $f : S^1 \times [0, \infty[ \rightarrow \mathbb{R}$  is bounded and solves

$$f_{\theta\theta} + f_{tt} - c^2 f = F(f, Df, D^2f),$$

where  $F$  is smooth and vanishes up to order 2 at  $(0, 0, 0)$ .

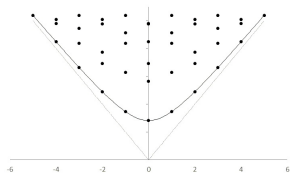
Then

$$f \sim \sum_{(\lambda, \mu) \in \mathcal{M}} a_{\lambda, \mu} e^{-i\lambda\theta} e^{\mu t}$$

where  $\mathcal{M}$  is the additive sub-semigroup of  $\mathbb{R} \times \mathbb{R}$  generated by

$$\mathcal{M}_0 := \left\{ (m, \sqrt{m^2 + c^2}) \mid m \in \mathbb{Z} \right\}.$$

## Structure of $\mathcal{M}$



After rescaling, the points  $(0, \sqrt{1-k})$  and  $(\pm 1, 1)$  are elements of  $\mathcal{M}$ .

The coefficient  $a_{0, \sqrt{1-k}}$  is the “radius” of the cusp.

The coefficients  $a_{\pm 1, 1}$  yield the Steiner geodesic.



Thankyou!